Stepping Motor Driver

Stepping Motor Driver recommendation

KSS provides recommended Stepping Motor Driver as an option in order to make it easy to use.

Precaution of Driver usage

Please adjust the run current according to the rated current of the Motor before use.

The adjustment method of the Run current is different for each driver. To adjust the Run current, it is available to down load each instruction manuals from KSS website and follow the steps to make the correct adjustment.

Standard Stepping Motor Driver

KR-A5CC

This Driver is for 5-phase Stepping Motor operated by DC24V power supply. It has automatic current reduction circuits. You can choose full-step or half step function.



KR-A55MC

Micro-Step Driver for 5-phase Stepping Motor with DC24V power supply. 16 step angle types can be set with up to 250 divisions.



KR-A535M

Micro-Step Driver for 5-phase Stepping Motor, which can be used with AC100~220V power supply. 16 step angle types can be set with up to 250 divisions.



SD4015B3

This is recommended Bipolar 2-phase stepping Motor Driver for rated current 0.25A/phase \sim 1.5A/phase. It has Micro-Step function with 8-step angle.



SD4030B3

This is recommended Bipolar 2-phase stepping Motor Driver for rated current 0.5A/phase \sim 3.0A/phase. It has Micro-Step function with 8-step angle.



Outer dimensions and specifications of KSS recommended Driver are shown from next page.

KR-A5CC

DC24V Input 5-phase Stepping Motor Driver

DC24V

0.1~0.9A / phase

Full / Half-Step

Case type

■Specifications

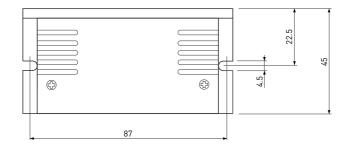


Description Description Description Description Read current : 0.1~0.9A/phase							-					
Diving Type	Items		Speci	fication								
Driving Type	Power supply	у	DC20	-35V(-10%,+20°	%) max.3A							
Signal name												
CW+ CW- CW- CW rotation input for 2 clock mode CW rotation input for 2 clock mode CW- Rotation input for 2 clock mode CW- Rotation input for 2 clock mode CCW- Rotation input for 2 clock Mode CCW- Rotation input for 2 clock Mode CCW- CCW rotation input for 2 clock Mode Mode Mode Mode Mode Mode Mode Mode	Driving Type		Bipola	ar pentagon cor	stant current drive							
CCW		Signal name	Funct	unctional description Input resistance								
CCW+ CW rotation input for 2 clock mode CCW+ CCW+		CW+	Pulse	signal input fo	r 1 clock mode			2000				
CCW CCW rotation input for 2 clock 390Ω		CW-	CW ro	tation input for	· 2 clock mode			37012				
H.O.+ H.O.+ H.O.+ H.O		CCW+						2000				
H. U.+ Motor exciting OFF 390Ω		CCW-	CCW	rotation input f	or 2 clock			37012				
Pulse width: 0.5µs min., Rising-up time: 10µs max. Pulse vidtade: "H" for 4~8V & "L" for 0~0.5V Triggerd at the edge of OFF (Logic "L") to ON (Logic"H") of photo-coupler current CCW rotation with CCW input of "L" in 1-clock system To change the RUN current, connect the CP+ to the (+) terminal of the voltmeter and the CP- to the (-) terminal of the voltmeter then adjust RUN CURRENT volume. Setting of driving current Setting example) When drive current is set to 0.35A/phase, the CP voltage is adjusted to 1.4V. Note) Run current should be changed during the operating of motor. Setting of Stop current In order to reduce the heat adjusting the current, change it using STOP CURRENT volume. The setting value of STOP CURRENT volume is a percentage of the setting volume of RUN CURRENT. Ex) After setting 1.4A for Run current then put STOP CURRENT volume at 50%, the stop current will be 0.7A. Setting of Dip-switches (All off at shipping) No. Symbol Function ON OFF 1 1/2 CLK Switching of clock 1 clock mode 2 clock mode 2 Full / Half Setting of Interpolation Full-step (0.72') Half-step (0.36')	circuit	H.O.+						3000				
Pulse interval: 0.5 ys min., Pulse frequency: 50kpps max. Pulse voltage: "H" for 4~8V & "L" for 0~0.5V Triggerd at the edge of OFF (Logic"L") to 0N (Logic"H") of photo-coupler current CCW rotation with CCW input of "L" in 1-clock system To change the RUN current, connect the CP+ to the (+) terminal of the voltmeter and the CP- to the (-) terminal of the voltmeter then adjust RUN CURRENT volume. Setting current (A) = CP voltage (V) Setting example) When drive current is set to 0.35A/phase, the CP voltage is adjusted to 1.4V. Note) Run current should be changed during the operating of motor. Setting of Stop current In order to reduce the heat adjusting the current, change it using STOP CURRENT volume. The setting value of STOP CURRENT volume is a percentage of the setting volume of RUN CURRENT. Ex) After setting 1.4A for Run current then put STOP CURRENT volume at 50%, the stop current will be 0.7A. No. Symbol Function ON OFF All off at shipping) No. Symbol Function ON OFF 1 1/2 CLK Switching of clock 1 clock mode 2 clock mode 2 Full / Half Setting of Interpolation Full-step (0.72') Half-step (0.36')		H.O	"H" fo	r motor excitin	g OFF			37022				
Setting of driving current Setting current (A) = CP voltage (V) / 4 Setting example) When drive current is set to 0.35A/phase, the CP voltage is adjusted to 1.4V. Note) Run current should be changed during the operating of motor. In order to reduce the heat adjusting the current, change it using STOP CURRENT volume. The setting value of STOP CURRENT volume is a percentage of the setting volume of RUN CURRENT. Ex) After setting 1.4A for Run current then put STOP CURRENT volume at 50%, the stop current will be 0.7A. Setting of Dip-switches (All off at shipping) No. Symbol Function ON OFF 1 1/2 CLK Switching of clock 1 clock mode 2 clock mode 2 Full / Half Setting of Interpolation Full-step (0.72') Half-step (0.36')			Pulse Pulse Trigge	Pulse interval : 0.5µs min., Pulse frequency : 50kpps max. Pulse voltage : "H" for 4~8V & "L" for 0~0.5V Triggerd at the edge of OFF (Logic"L") to ON (Logic"H") of photo-coupler current								
Setting example) When drive current is set to 0.35A/phase, the CP voltage is adjusted to 1.4V. Note) Run current should be changed during the operating of motor. In order to reduce the heat adjusting the current, change it using STOP CURRENT volume. The setting value of STOP CURRENT volume is a percentage of the setting volume of RUN CURRENT. Ex) After setting 1.4A for Run current then put STOP CURRENT volume at 50%, the stop current will be 0.7A. Setting of Dip-switches (All off at shipping) No. Symbol Function ON OFF 1 1/2 CLK Switching of clock 1 clock mode 2 clock mode 2 Full / Half Setting of Interpolation Full-step (0.72') Half-step (0.36')												
Setting of Stop current In order to reduce the heat adjusting the current, change it using STOP CURRENT volume. The setting value of STOP CURRENT volume is a percentage of the setting volume of RUN CURRENT. Ex) After setting 1.4A for Run current then put STOP CURRENT volume at 50%, the stop current will be 0.7A. Setting of Dip-switches (All off at shipping) No. Symbol Function ON OFF 1 1/2 CLK Switching of clock 1 clock mode 2 clock mode 2 Full / Half Setting of Interpolation Full-step (0.72*) Half-step (0.36*)	Setting of dri	iving current	Setting example) When drive current is set to 0.35A/phase, the CP voltage is									
The setting value of STOP CURRENT volume is a percentage of the setting volume of RUN CURRENT. Ex) After setting 1.4A for Run current then put STOP CURRENT volume at 50%, the stop current will be 0.7A. Setting of Dip-switches (All off at shipping) No. Symbol Function ON OFF 1 1/2 CLK Switching of clock 1 clock mode 2 clock mode 2 Full / Half Setting of Interpolation Full-step (0.72°) Half-step (0.36°)			Note)	Run current sh	nould be changed during	the operating of motor.						
Setting of Dip-switches (All off at shipping) 1 1/2 CLK Switching of clock 1 clock mode 2 clock mode 2 Full / Half Setting of Interpolation Full-step (0.72°) Half-step (0.36°)	Setting of Sto	op current	The setting value of STOP CURRENT volume is a percentage of the setting volume of RUN CURRENT. Ex) After setting 1.4A for Run current then put STOP CURRENT volume at 50%, the stop current will be 0.7A.									
Setting of Dip-switches (All off at shipping) 1 1/2 CLK Switching of clock 1 clock mode 2 clock mode 2 Full / Half Setting of Interpolation Full-step (0.72°) Half-step (0.36°)			No. Symbol Function ON OFF									
Z Full / Half Setting of Interpolation Full-Step (0.72) Half-step (0.36)			1	,	Switching of clock	1 clock mode	2 clock mode	0FF ↓ ↓ ≥12				
Operating temperature & humidity 0~40℃ 85%RH max. without any dew condensation.			2	Full / Half	Setting of Interpolation	Full-step (0.72°)	Half-step (0.36°)	ON EDD				
	Operating ter	mperature & humidity	0~40	0~40°C 85%RH max. without any dew condensation.								

Driver Outer Dimensions

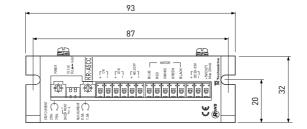
Storage temperature & humidity

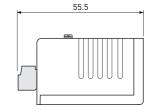
Mass



Approximately 130g

-10~70°C 85%RH max. without any dew condensation.





V101

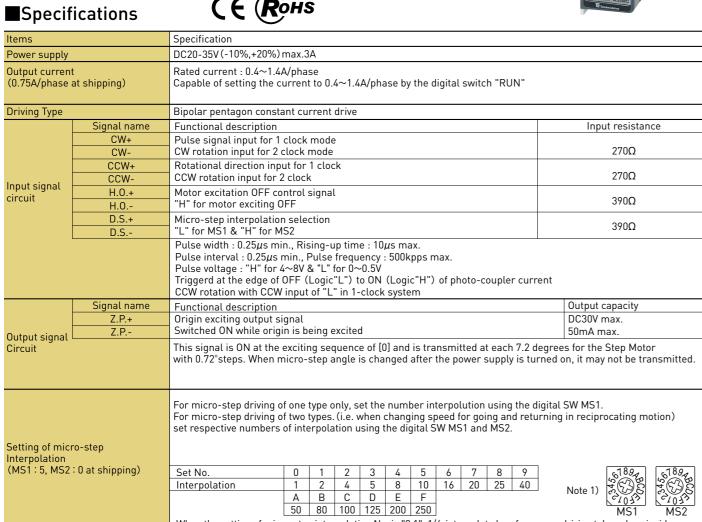
DC24V Input Microstep Driver

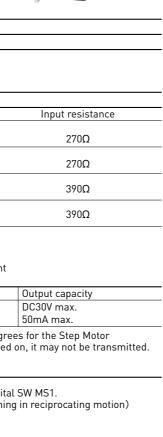
0.4~1.4A / phase

KR-A55MC

DC24V







When the setting of micro-step interpolating No. is "0.1", 1/4-interpolate low-frequency driving takes place inside.

Setting of driving current	The output current to the	moto	r in ro	tation	is set	by the	e digita	al swit	ch "R	UN" to	selec	t from the table below.
(Setting "5" at shipping)	Set No.	0	1	2	3	4	5	6	7	8	9	
	Current (A)	0.4	0.5	0.57	0.63	0.71	0.77	0.84	0.9	0.96	1.02	
		Α	В	С	D	E	F					
		1.09	1.15	1.22	1.27	1.33	1.4					



Automatic current-down
(Setting "5" at shipping)
(Setting 5 at shipping)

The output current to the motor at stationary is set by the digital switch "STOP" to select from the table below. The value is set by the percent to "RUN" current. The current decreases at approx. 500ms after the last pulse.

設定番号 Set No.	0	1	2	3	4	5	6	7	8	9
(%)	27	31	36	40	45	50	54	58	62	66
	Α	В	С	D	Ε	F				
	70	74	78	82	86	90				

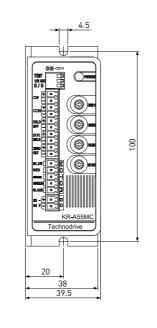


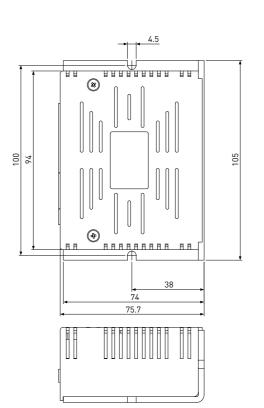
Items	Specif	ication								
	No.	symbol	Function	ON	OFF					
Setting of dip-switches	1	TEST Self test function		Rotating at 250pps	Normal operation	123				
(All off at shipping)	2	1/2 CLK	Switching of clock	1 clock mode	2 clock mode	ON ← OFF				
	3 C / D Automatic curr		Automatic current-down	Invaild	Vaild	Note2				
Operating temperature & humidity	0 ~ 40	0℃ 85%RH	Max. without any condens	sation.						
Storage temperature & humidity	-10 ~	$10\sim70^\circ\text{C}$ 85%RH Max. without any dew condensation.								
Mass	Appro	pproximately 220g								

Note 1) Micro-step angle for 1 pulse=Basic step angle / Number of interpolation

Note 2) Approx. 250pps is generated inside, regardless of splits setting; CCW rotation when the dip switch NO.2 is ON, and CW rotation when the dip switch NO.2 is OFF.

Driver Outer Dimensions





Stepping Motor Drive

Stepping Motor Driver

V103

KR-A535M

AC100-220V Input Microstep Driver

AC100-220V

0.4~1.4A / phase

Micro-step



(E Rons **■**Specifications

Specification Power supply AC100-220V (±10%) max.3A 50/60Hz

1 1 1 1 1 1	,							
Output curr (0.75A/phas	ent e at shipping)	Rated current : $0.4\sim1.4$ A/phase Capable of setting the current to $0.4\sim1.4$ A/phase by the digital switch "RUN"						
Driving Type	?	Bipolar pentagon constant current drive	_					
	Signal name	Functional description	Input resistance					
	CW+	Pulse signal input for 1 clock mode	2700					
	CW-	CW rotation input for 2 clock mode	270Ω					
	CCW+	Rotational direction input for 1 clock	270Ω					
In most allowed	CCW-	CCW rotation input for 2 clock	27012					
Input signal circuit	H.O.+	390Ω						
H.U		"H" for motor exciting OFF	37012					
	D.S.+	Micro-step interpolation selection	390Ω					
	D.S	"L" for MS1 & "H" for MS2	57022					
		Pulse width : $0.25\mu s$ min., Rising-up time : $10\mu s$ max. Pulse interval : $0.25\mu s$ min., Pulse frequency : $500kpps$ max. Pulse voltage : "H" for $4\sim8V$ & "L" for $0\sim0.5V$						
		Triggerd at the edge of OFF (Logic"L") to ON (Logic"H") of photo-coupler current CCW rotation with CCW input of "L" in 1-clock system						
	Signal name	Functional description	Output capacity					
Output	Z.P.+	Origin exciting output signal	DC30V max.					
signal Z.P Switched ON while origin is being excited		Switched ON while origin is being excited	50mA max.					
Circuit			This signal is ON at the exciting sequence of [0] and is transmitted at each 7.2 degrees for the Step Motor with 0.72° steps. When micro-step angle is changed after the power supply is turned on, it may not be transmitted.					

Setting of micro-step
interpolation
(MS1:5 MS2:0 at chinning)

For micro-step driving of one type only, set the number interpolution using the digital SW MS1. For micro-step driving of two types. (i.e. when changing speed for going and returning in reciprocating motion) set respective numbers of interpolation using the digital SW MS1 and MS2.

Set No.	0	1	2	3	4	5	6	7	8	9
Interpolation	1	2	4	5	8	10	16	20	25	40
	Α	В	С	D	Е	F				
	50	80	100	125	200	250				



Note) When the setting of micro-step interpolating No. is "0.1", 1/4-interpolate low-frequency driving takes place inside. The output current to the motor in rotation is set by the digital switch "RUN" to select from the table below.

Setting of driving current (Setting "5" at shipping)	Set No.	0	1	2	3	4	5	6	7	8	9
(Setting 5 at Snipping)	Current (A)	0.4	0.5	0.57	0.63	0.71	0.77	0.84	0.9	0.96	1.02
		Α	В	С	D	Е	F				
		1.09	1.15	1.22	1.27	1.33	1.4				



Automatic current-down (Setting "5" at shipping)

The output current to the motor at stationary is set by the digital switch "STOP" to select from the table below. The value is set by the percent to "RUN" current. The current decreases at approx. 500ms after the last pulse.

Set No.	0	1	2	3	4	5	6	7	8	9
(%)	27	31	36	40	45	50	54	58	62	66
	Α	В	С	D	Е	F				
	70	74	78	82	86	90				

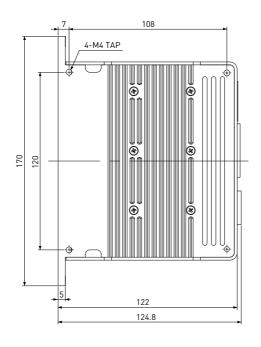


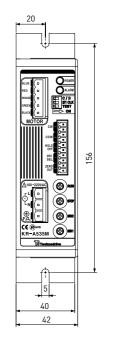
Items	Specif	pecification								
	No.	symbol	Function	ON	OFF					
Setting of dip-switches	1 TEST Self test function		Rotating at 250pps	Normal operation	2 H 1 NoU					
(All off at shipping)	2	2 1/2 CLK Switching of clock		1 clock mode	2 clock mode	OFF → ON				
	3 C / D Automatic current-down		Invaild	Vaild	Note2					
Operating temperature & humidity	0 ~ 40	0°C 85%RH	Max. without any condens	sation.						
Storage temperature & humidity	-10 ~	-10 ~ 70℃ 85%RH Max. without any dew condensation.								
Mass	Appro	pproximately 660g								

Note 1) Micro-step angle for 1 pulse=Basic step angle / Number of interpolation

Note 2) Approx. 250pps is generated inside, regardless of splits setting; CCW rotation when the dip switch N0.2 is ON, and CW rotation when the dip switch N0.2 is OFF.

Driver Outer Dimensions





Stepping Motor Driver

V105 V106

DC24V Input 2-phase Stepping Motor Driver

DC24V

 $0.25 \sim 1.5 \text{A} / \text{phase}$

Full / half step

Board type

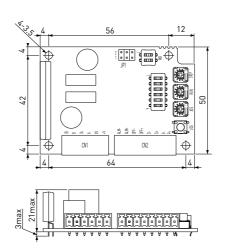


■Specifications

C€	R ons
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	=Specifications (Constitutions)						
	Items		Description	Note			
	Input voltagee		DC+18V~36V				
	Output current		0.25~1.5Apeak(±5%)/phase	Being lower rated output current beyond Power Supply 24V			
	Drive method		Chopper mode by Bipolar constant current	It can be used for uni-polar type.			
	Current down function		Auto Current down Adjusting to set lower current of CND volume about 0.25 \sim 1 second after pulse stop	Selectable by switch.			
	Maximum input pulse cycle		200Kpps				
	Adjusting	RUN	For excitation current (0.25~1.5A)	The default factory setting is 1A.			
		STOP	For current down value on current down mode.	Selectable between 10% to 60% of RUN current.			
		MIX	Mixed Decay ratio (0%、20%、40%、80%)	The default factory setting is 80%			
		JOG	For JOG speed setting.	300pps~14Kpps			
	Select function	SW-1,2,3	Select of Resolutions	1/2, 1/8, 1/10, 1/16, 1/20, 1/32, 1/40, 1/64			
		SW-4	ON/OFF for function of auto current down mode.	Switch ON is active and OFF is no active. The default factory setting is ON.			
		SW-5,6	Select of JOG function	SW-5 ON is active for JOG, SW6 ON is CW, OFF is CCW			
		SW-3	Select of Mix-Decay ratio				
		JP1	Select of 1-pulse, 2-pulse				
	Input signals	P+,P-	Pulse Command	Selection of 1 pulse an 2 pulse for pulse command. Isolated by photo coupler			
		D+,D-	Direction Command				
		OFF+,OFF-	No excitation				
	Output signals	ALM+,ALM-	Alarm (Prospecting of over-heat for Power device) Output at over 170°C (Typ.) of power device	Photo Isolation, ON is active, OFF is no active (ALARM).			
	Dimension		W72×D50×H21				
	Operating Temperature and Humidity		0~40°C,35~80% RH	No condensation			
	Storage Temperature	e and Humidity	-20~+85℃、35~80% RH	No condensation			
Mass			Approximately 40g				

Driver Outer Dimensions



DC24V Input 2-phase Microstep Driver

DC24V

0.5~3A / phase

Micro-sten

Board type

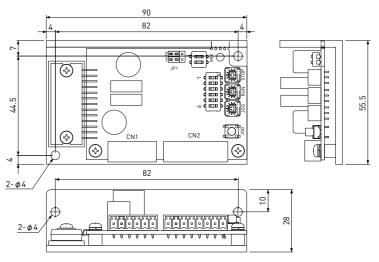
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■Specifications

$C \in \mathcal{C}$	R ons
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Items		Description	Note
Input voltagee		DC+18V~36V	
Output current		0.5~3 A peak(±5%)/phase	Being lower rated output current beyond Power Supply 24V
Drive method		Chopper mode by Bipolar constant current	It can be used for uni-polar type.
Current down function		Auto Current down Adjusting to set lower current of CND volume about 0.7 second after pulse stop	Selectable by switch.
Maximum input pulse cycle		200Kpps	
Adjusting	RUN	For excitation current (0.5~3A)	The default factory setting is 2A.
	STOP	For current down value on current down mode.	Selectable between 10% to 60% of RUN current.
	MIX	Mixed Decay ratio (0%、20%、40%、80%)	The default factory setting is 80%
	JOG	For JOG speed setting.	300pps~14Kpps
Select function	SW-1,2,3	Select of Resolutions	1/2, 1/8, 1/10, 1/16, 1/20, 1/32, 1/40, 1/64
	SW-4	ON/OFF for function of auto current down mode.	Switch ON is active and OFF is no active. The default factory setting is ON.
	SW-5,6	Select of JOG function	SW-5 ON is active for JOG, SW6 ON is CW, OFF is CCW
	SW-3	Select of Mix-Decay ratio	
	JP1	Select of 1-pulse, 2-pulse	
Input signals	P+,P-	Pulse Command	Selection of 1 pulse an 2 pulse for pulse command. Isolated by photo coupler
	D+,D-	Direction Command	
	0FF+,0FF-	No excitation	
Output signals	ALM+,ALM-	Alarm (Prospecting of over-heat for Power device) Output at over 170°C (Typ.) of power device	Photo Isolation, ON is active, OFF is no active(ALARM).
Dimension		W90×D55.5×H28	
Operating Temperature and Humidity		0~40℃,35~80% RH	No condensation
Storage Temperature and Humidity		-20~+85℃,35~80% RH	No condensation
Mass		Approximately 112g	

Driver Outer Dimensions



V107