AC100-220V Input Microstep Driver

AC100-220V

Micro-step



STOP

(€ RoHs

■ Spe	ecifications												T Table 200
Items		Specification											
Powers	supply	AC100-220V (±10%) ma	ax.3A	50/60)Hz								
Output (0.75A/	current phase at shipping)	Rated current : 0.4~1.4 Capable of setting the o).4~1.	4A/ph	nase b	y the	digital	swit	ch "RU	N"	
Driving	Туре	Bipolar pentagon const	ant c	urren	t drive	9							
	Signal name	Functional description								Input resistance			
	CW+	Pulse signal input for 1											270Ω
	CW-	CW rotation input for 2 clock mode Rotational direction input for 1 clock										2,012	
	CCW+	CCW rotation input for 2 clock										270Ω	
	H.O.+	Motor exciting OFF control signal											
In most of most	НО-	"H" for motor exciting OFF									390Ω		
Input sigr	D.5.+	Micro-step interpolation selection										390Ω	
Circuit	D.S	"L" for MS1 & "H" for MS2											37002
		Pulse width: 0.25µs mir Pulse interval: 0.25µs m Pulse voltage: "H" for 4 Triggerd at the edge of OF CCW rotation with CCW	nin., F ~8V 8 F (Lo	ulse f k "L" fo gic"L'	reque or 0~0 ') to 01	ncy : 5).5V N (Log	i00kpr gic"H";) of ph		upler	current	:	
	Signal name	Functional description											Output capacity
	Z.P.+	Origin exciting output signal										DC30V max.	
0	Z.P	Switched ON while origin is being excited										50mA max.	
Output s Circuit	signal	This signal is ON at the for the Step Motor with turned on,it may not be	0.72	steps	. Whe								
interpol	of micro-step lation i, MS2 : 0 at shipping)	For micro-step driving For micro-step driving (i.e. when changing sp set respective numbers	of two	o type or goi	s. ng and lation	d retu using	rning g the o	in red digital	ciproca SW M	ating IS1 ar	motion nd MS2)	digital SW MS1.
		Set No.	0	1	2	3	4	5	6	7	8	9	G189 ₂ G189 ₂
		Interpolation	1 A	2 B	4 C	5 D	8 E	10 F	16	20	25	40	36,34
			50	80	100	125	200	250					(2/03) (2/03)
		Note) When the setting 1/4-interpolate	g of n	nicro-	step i	nterp	olatin	g No.					MS1 MS2
	of driving current g "5" at shipping)	The output current to the motor in rotation is set by the digital switch "RUN" to select from the table below.											
(00111119	, o atompping,	Set No.	0	1	2	3	4	5	6	7	8	9	6189
		Current (A)	0.4	0.5					0.84	0.9	0.96	1.02	4500
		-	1 no	1 15	C 1.22	D 1 27	1 22	F 1.4	-				RUN
		The output current to the							o d:~:1	al av	itch "C	TOD"	to coloct from
	tic current-down g "5" at shipping)	the table below.				-		i by th	ie aigit	.dl SW	nich S	TUP	to select from

The value is set by the percent to "RUN" current.
The current decreases at approx. 500ms after the last pulse.

Set No. (%)

 0
 1
 2
 3
 4
 5
 6
 7
 8
 9

 27
 31
 36
 40
 45
 50
 54
 58
 62
 66

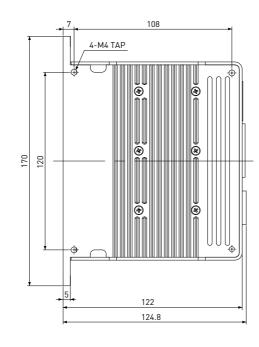
 A
 B
 C
 D
 E
 F

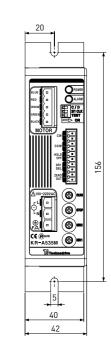
 70
 74
 78
 82
 86
 90

Items	Specification									
	No.	symbol	Function	ON	OFF					
Setting of dip-switches	1	TEST	Self test function	Rotating at 250pps	Normal operation					
(All off at shipping)	2	1/2 CLK	Switching of clock	1 clock mode	2 clock mode	OFF → ON				
	3	C/D	Automatic current-down	Invaild	Vaild	note2				
Operating temperature & humidity	$0 \sim 40 ^{\circ} \text{C}$ 85%RH Max. without any condensation.									
Storage temperature & humidity	-10 \sim 70°C 85%RH Max. without any dew condensation.									
Mass	Approximately 660g									

Note 1) Micro-step angle for 1 pulse=Basic step angle / Number of interpolation
Note 2) Approx. 250pps is generated inside, regardless of splits setting; CCW rotation when the dip switch N0.2 is ON, and CW rotation when the dip switch N0.2 is OFF.

Driver Outer Dimensions





Stepping Motor Driver